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Berlin, February 07, 2001

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Sub: **Analysis of Everest** constructed test data
 here: Basic analysis of **data corrected** and evaluation
 according to proposed rational method
 Ref.: Evaluations of ISO_fin4 to fin7.mcd
 Evaluations of **EVEREST_01 to 06.mcd**
 Tamura, K.: 'An Appraisal of correction Methods ...'
 Trans. West-Japan S.N.A (1999) No. 97, 11-24
 .
 Letter by Prof. Tamura dated 06.01.2001
 Letters by Prof. Schmiechen dated 03./04.02.2001

Note:

This version **EVEREST_07** differs from the preceding version EVEREST_06 only:
1. by a more adequate notation for the averages, which have only been introduced
 for comparison with the results of the traditional method, but **which are not essential
 for the present method**,
2. by a statistical analysis of the distribution of deviations of power and speed
 results according to the rational evaluation of the individual runs, and
3. by additional plots of final results, interpolated and normalised values in particular.

Analysis of EVEREST constructed data

Units	Speed	$kn := \frac{1852 \cdot m}{3600 \cdot sec}$
	Power	$W := watt$ $MW := 10^3 \cdot kW$
Test identification	TID := "EVEREST"	
Constants	Length of ship	$L := 213 \cdot m$ $L := \frac{L}{m}$
	Diameter of propeller	$D := 6.6 \cdot m$ $D := \frac{D}{m}$
	Density of sea water	$\rho := 1.025 \cdot 10^3 \cdot kg \cdot m^{-3}$ $\rho := \frac{\rho}{kg \cdot m^{-3}}$
		$g := 9.81 \cdot m \cdot sec^{-2}$ $g := \frac{g}{m \cdot sec^{-2}}$

Functions and subroutines

Compute left-inverse

```
LeftInv(A) := | r ← rows(A)
                | c ← cols(A)
                | s ← svds(A)
                | for i ∈ 0..c - 1
                |   ISVi,i ← (si)-1
                |   UV ← svd(A)
                |   U ← submatrix(UV, 0, r - 1, 0, c - 1)
                |   V ← submatrix(UV, r, r + c - 1, 0, c - 1)
                |   Ainv.left ← V · ISV · UT
                |
                | Ainv.left
```

Compute power

$$P_{\text{sup}}(p, N, V) := p_0 \cdot N^3 + p_1 \cdot N^2 \cdot V \quad P_{\text{req}}(C, V) := C_0 \cdot V + C_1 \cdot V^2 + C_2 \cdot V^3$$

Compute frequency of revolutions

```
Revs(p, V, P, N) := | ni ← last(V)
                      | for i ∈ 0..ni
                      |   q0 ← Pi
                      |   q1 ← Vi
                      |   n ← Ni
                      |   Nrati ← root(q0 - p0 · n3 - p1 · n2 · q1, n)
                      |
                      | Nrat
```

Normalise data

$$JH(V, N) := \frac{V}{D \cdot N} \quad KP(P, N) := \frac{P}{\rho \cdot D^5 \cdot (N)^3}$$

$$Fn(V) := \frac{V}{\sqrt{g \cdot L}} \quad CP(P, V) := \frac{P}{\rho \cdot D^2 \cdot (V)^3}$$

Analyse power supplied

```

Supplied(D, ρ, t, ψ₀, V_G, N, P_S) := | for i ∈ 0..last(t)
                                             |   A_supᵢ₀ ← (Nᵢ)³
                                             |   A_supᵢ₁ ← (Nᵢ)² · V_Gᵢ
                                             |   d_FMᵢ ← if(ψ₀ < π, -1, 1)
                                             |   A_supᵢ₂ ← (Nᵢ)² · d_FMᵢ · cos(2 · π · tᵢ / 12)
                                             |   A_supᵢ₃ ← (Nᵢ)² · d_FMᵢ · sin(2 · π · tᵢ / 12)
                                             |
                                             | X_sup ← LeftInv(A_sup) · P_S
                                             | E_sup ← P_S - A_sup · X_sup
                                             | p₀ ← X_sup₀
                                             | p₁ ← X_sup₁
                                             |
                                             | for j ∈ 0..1
                                             |   vⱼ ← X_sup₂+j / X_sup₁
                                             |
                                             | for i ∈ 0..last(t)
                                             |   V_F.ratᵢ ← v₀ · cos(2 · π · tᵢ / 12) + v₁ · sin(2 · π · tᵢ / 12)
                                             |   V_S0.ratᵢ ← V_Gᵢ + V_F.ratᵢ · d_FMᵢ
                                             |   P_S.ratᵢ ← p₀ · (Nᵢ)³ + p₁ · (Nᵢ)² · V_S0.ratᵢ
                                             |   J_H.ratᵢ ← V_S0.ratᵢ / (D · Nᵢ)
                                             |   K_P.ratᵢ ← P_S.ratᵢ / (ρ · D⁵ · (Nᵢ)³)
                                             |
                                             | [E_sup V_F.rat V_S0.rat P_S.rat J_H.rat K_P.rat p]

```

The harmonic current model has been introduced in accordance with the test data.

Analyse power required

```

Required(V_S0, P_S, V_WindR.x) := | for i ∈ 0..last(V_S0)
                                         |   A reqi,0 ← (V_S0i)1
                                         |   A reqi,1 ← (V_S0i)2
                                         |   A reqi,2 ← (V_S0i)3
                                         |   A reqi,3 ← V_WindR.xi | V_WindR.xi | · V_S0i
                                         |
                                         | X req ← LeftInv(A req) · P_S
                                         |
                                         | E req ← P_S - A req · X req
                                         |
                                         | P_AWind ← A req <<3> · X req3
                                         |
                                         | for i ∈ 0..last(V_S0)
                                         |
                                         |   P_AAiri ← (V_S0i)3 · X req3
                                         |
                                         | P_S0.vacuo ← P_S - P_AWind
                                         |
                                         | [E req P_AWind P_S0.vacuo X req]

```

The reduction to the power required in vacuo permits direct comparison
of the results of the various runs in this particular test case.

Check distribution of residua

```

Norm_distr(Sampl) := | r←rows( Sampl)
                      | c←cols( Sampl)
                      | for i ∈ 0..r - 1
                      |   fract← $\frac{2\cdot(i+1)}{r+1} - 1$ 
                      |   distr←fract
                      |   Distri← $\sqrt{2 \cdot \text{root}(\text{erf}(distr) - fract, distr)}$ 
                      |   for j ∈ 0..1
                      |     Ai,j←(Distri)j
                      |   for j ∈ 0..c - 1
                      |     Samplsort <j>←sort(Sampl<j>)
                      | Par←LeftInv( A )·Samplsort
                      | Samplsort.fair←A·Par
                      | for j ∈ 0..c - 1
                      |   Par2,j← $\frac{\text{Par}_{1,j}}{\sqrt{r}}$ 
                      |   [ Distr
                      |     Samplsort
                      |     Samplsort.fair
                      |     Par ]

```

Data supplied with files

$\text{Data} := \text{READPRN}(\text{"data.txt"})^T$

time	course	speed over ground
------	--------	-------------------

$t_{\text{File}} := \text{Data}^{<0>} \cdot \text{min}$	$\psi_0_{\text{File}} := \text{Data}^{<1>} \cdot \text{deg}$	$V_G_{\text{File}} := \text{Data}^{<2>} \cdot \text{kn}$
---	--	--

frequencies of revolution:

brake powers measured:

$N_{\text{File}} := (\text{submatrix}(\text{Data}, 0, 11, 3, 8)) \cdot \text{min}^{-1}$ $P_S_{\text{File}} := \text{submatrix}(\text{Data}, 0, 11, 9, 14) \cdot \text{mhp}$

$n_i := \text{rows}(N_{\text{File}})$ $n_i = 12.00$

$n_j := \text{cols}(N_{\text{File}})$ $n_j = 6.00$

$i := 0 .. n_i - 1$

$j := 0 .. n_j - 1$

Time data replaced by correct values 03.02.2001

$$t := \begin{bmatrix} 0.00 \\ 1.10 \\ 2.10 \\ 3.00 \\ 3.45 \\ 4.25 \end{bmatrix} \cdot \text{hr}$$

Data reorganised

$\psi_0_j := \psi_0_{\text{File}_j}$

$V_G_j := V_G_{\text{File}_j}$

$N_{10} := (\text{submatrix}(N_{\text{File}}, 0, n_j - 1, 0, n_j - 1))$

$N_{20} := (\text{submatrix}(N_{\text{File}}, n_j, n_i - 1, 0, n_j - 1))$

$N := \text{augment}(N_{10}, N_{20})$

$P_{S.10} := (\text{submatrix}(P_S_{\text{File}}, 0, n_j - 1, 0, n_j - 1))$

$P_{S.20} := (\text{submatrix}(P_S_{\text{File}}, n_j, n_i - 1, 0, n_j - 1))$

$P_S := \text{augment}(P_{S.10}, P_{S.20})$

Data in SI units except for time in view of further use in some mathematical subroutines,
which by definition cannot handle arguments with (different) dimensions

$$t := \frac{t}{\text{hr}}$$

$$\psi_0 := \frac{\psi_0}{\text{rad}}$$

$$V_G := \frac{V_G}{\text{m} \cdot \text{sec}^{-1}}$$

$$N := \frac{N}{\text{Hz}}$$

$$P_S := \frac{P_S}{W}$$

Power supplied

```
ni := rows(N)      ni = 6.00      nj := cols(N)      nj = 12.00
i := 0 .. ni - 1          j := 0 .. nj - 1
```

Stacked data

```
j := 1 .. nj - 1
S0 := t
Sj := stack(Sj-1, t)      ts := Snj-1
S0 := ψ0
Sj := stack(Sj-1, ψ0)      ψ0.s := Snj-1
S0 := VG
Sj := stack(Sj-1, VG)      VG.s := Snj-1
S0 := N<0>
Sj := stack(Sj-1, N<j>)      ns := Snj-1
S0 := PS<0>
Sj := stack(Sj-1, PS<j>)      PS.s := Snj-1
j := 0 .. nj - 1
```

Evaluation

$$\text{Res}_{\text{sup}_j} := \text{Supplied}(D, \rho, t, \psi_0, V_G, N^{<j>}, P_S^{<j>})$$

$$\left[E_{\text{sup}}^{<j>} \ V_{F.\text{rat}}^{<j>} \ V_{S0.\text{rat}}^{<j>} \ P_{S.\text{rat}}^{<j>} \ J_{H.\text{rat}}^{<j>} \ K_{P.\text{rat}}^{<j>} \ p_{\text{rat}}^{<j>} \right] := \text{Res}_{\text{sup}_j}$$

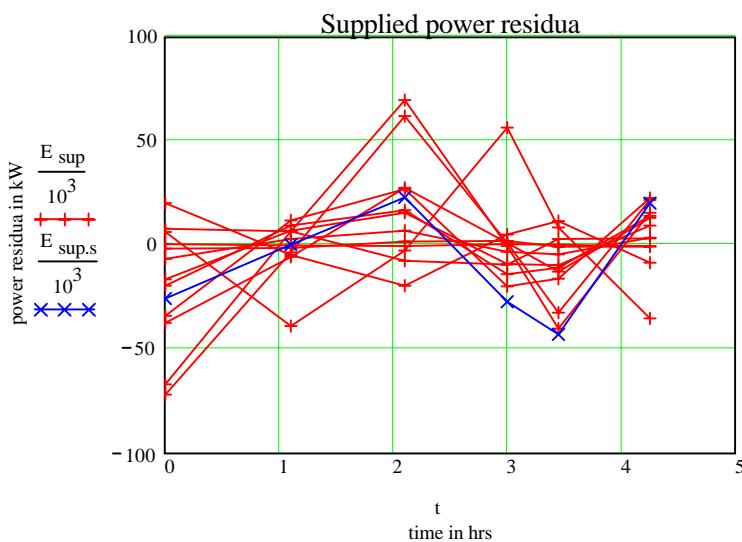
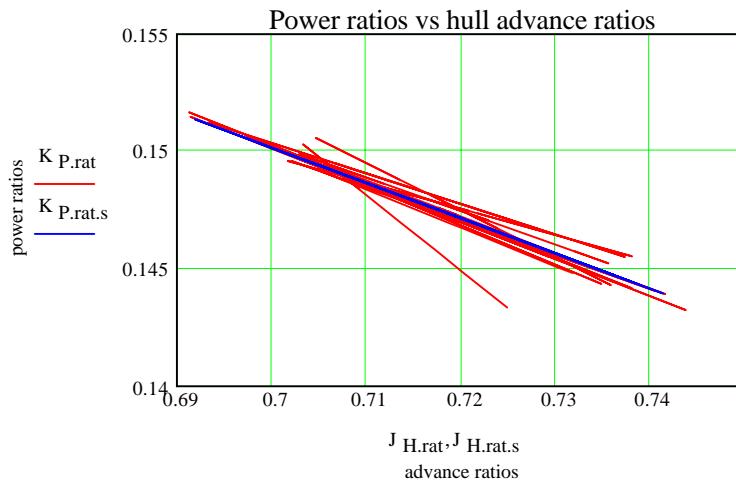
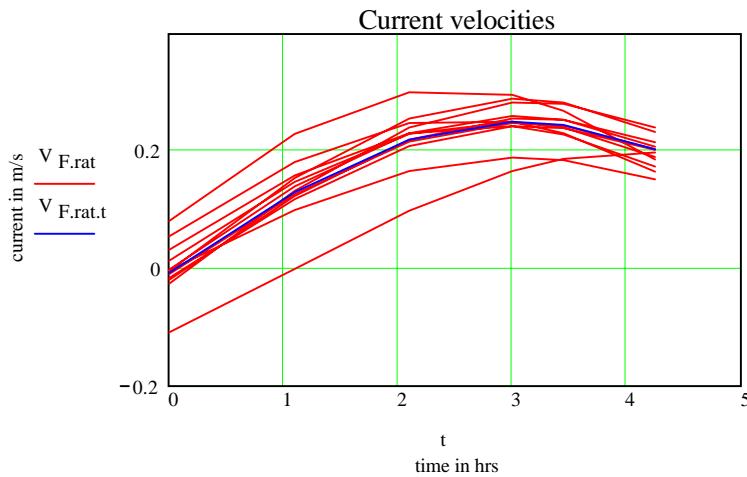
$$\text{Res}_{\text{sup}.s} := \text{Supplied}(D, \rho, t_s, \psi_{0.s}, V_{G.s}, n_s, P_{S.s})$$

$$\left[E_{\text{sup}.s} \ V_{F.\text{rat}.t} \ V_{S0.\text{rat}.s0} \ P_{S.\text{rat}.s} \ J_{H.\text{rat}.s} \ K_{P.\text{rat}.s} \ p_{\text{rat}.s} \right] := \text{Res}_{\text{sup}.s}$$

$$V_{F.\text{rat}.s_i} := V_{F.\text{rat}.t_i}$$

$$V_{S0.\text{rat}.s_i} := V_{S0.\text{rat}.s0_i}$$

**Plots of current velocities
identified by rational method**



These results show, that the data are not only noisy,
but that some power values are even inconsistent.

$$\frac{E_{\text{sup}}}{10^3} = \begin{bmatrix} -33.97 & 20.18 & -19.61 & 0.44 & -16.43 & -6.73 & -1.76 & -37.53 & 7.72 & 6.38 & -71.72 & -66.83 \\ 11.73 & -4.63 & 9.48 & -0.28 & 6.98 & 2.85 & -1.50 & -5.84 & 6.55 & -38.79 & -3.61 & 6.74 \\ 26.81 & -19.39 & 16.83 & -0.43 & 15.51 & 6.88 & 1.68 & 27.39 & -7.53 & -2.55 & 61.96 & 69.73 \\ -19.97 & 5.22 & -13.85 & 0.35 & -8.94 & -3.18 & 2.11 & 1.05 & -9.49 & 56.49 & 1.19 & -0.34 \\ -16.14 & 11.56 & -10.80 & 0.29 & -9.82 & -4.38 & -0.63 & -12.65 & 2.86 & 8.60 & -32.45 & -40.04 \\ 22.67 & -8.31 & 13.86 & -0.32 & 9.53 & 3.42 & -0.72 & 12.97 & 3.38 & -35.35 & 21.54 & 15.39 \end{bmatrix}$$

Relative residuals $e_{\text{sup}_{i,j}} := \frac{E_{\text{sup}_{i,j}}}{P_{S_{i,j}}}$

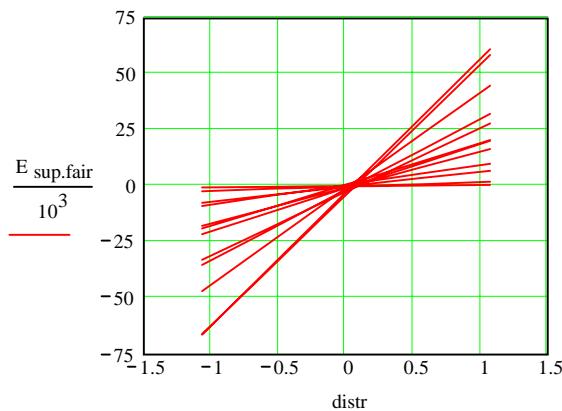
$$\frac{e_{\text{sup}}}{\%} = \begin{bmatrix} -0.54 & 0.32 & -0.31 & 0.01 & -0.26 & -0.11 & -0.03 & -0.55 & 0.11 & 0.10 & -1.10 & -1.07 \\ 0.20 & -0.08 & 0.16 & -0.00 & 0.11 & 0.05 & -0.03 & -0.10 & 0.11 & -0.65 & -0.06 & 0.11 \\ 0.27 & -0.19 & 0.17 & -0.00 & 0.16 & 0.07 & 0.02 & 0.25 & -0.07 & -0.02 & 0.60 & 0.69 \\ -0.21 & 0.05 & -0.14 & 0.00 & -0.09 & -0.03 & 0.02 & 0.01 & -0.10 & 0.59 & 0.01 & -0.00 \\ -0.13 & 0.09 & -0.08 & 0.00 & -0.08 & -0.03 & -0.00 & -0.09 & 0.02 & 0.06 & -0.25 & -0.31 \\ 0.19 & -0.07 & 0.11 & -0.00 & 0.08 & 0.03 & -0.01 & 0.11 & 0.03 & -0.29 & 0.17 & 0.12 \end{bmatrix}$$

Further analysis

Statistical analysis

Check of distributions

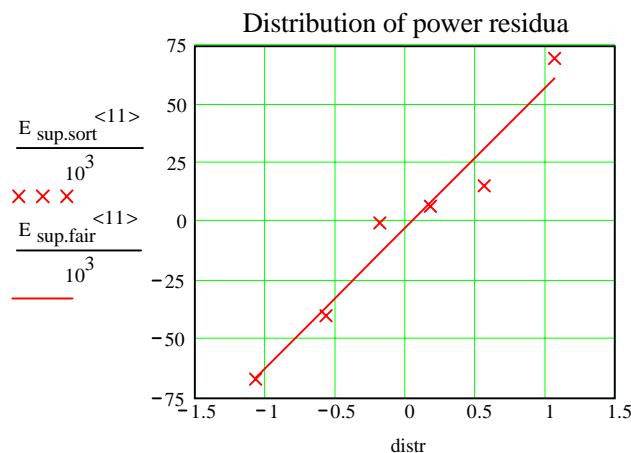
$$\begin{bmatrix} \text{distr} \\ E_{\text{sup.sort}} \\ E_{\text{sup.fair}} \\ \text{par} \end{bmatrix} := \text{Norm_distr}(E_{\text{sup}})$$



The data of the various runs
are of very different quality.

$$\frac{E_{\text{sup.sort}}}{10^3} = \begin{bmatrix} -34 & -19 & -20 & -0 & -16 & -7 & -2 & -38 & -9 & -39 & -72 & -67 \\ -20 & -8 & -14 & -0 & -10 & -4 & -1 & -13 & -8 & -35 & -32 & -40 \\ -16 & -5 & -11 & -0 & -9 & -3 & -1 & -6 & 3 & -3 & -4 & -0 \\ 12 & 5 & 9 & 0 & 7 & 3 & -1 & 1 & 3 & 6 & 1 & 7 \\ 23 & 12 & 14 & 0 & 10 & 3 & 2 & 13 & 7 & 9 & 22 & 15 \\ 27 & 20 & 17 & 0 & 16 & 7 & 2 & 27 & 8 & 56 & 62 & 70 \end{bmatrix}$$

Detailed pictures of the distributions show,
that often the errors are not normally distributed.
As an example the distribution is being plotted
for run 11 (2 - 6), which later be excluded
from the evaluation of the power required..



According to this analysis only in the two cases 3 (1 - 4) and 6 (2 - 1)
the data show hardly any noise, but in case 6 there are systematic problems,
as far as the current is concerned.

Heavy systematic effects are also observed in the last cases 9, 10 and 11.
But despite the noise the power ratios are perfect
except for the cases 1(1 - 2), 9 (2 - 4), 10 (2 - 5), 11(2 - 6).

Further analysis

**In this test case the repeated runs with the same ship
at the same current permits further analysis.**

The following results suggest that the velocities are the same down and up the current.
And in fact this has been assumed in generating the test data.

For the analysis in general this step is not necessary, even wrong!

$$V_{S0.rat.s} = \begin{bmatrix} 7.21 \\ 7.18 \\ 8.24 \\ 8.22 \\ 8.74 \\ 8.76 \end{bmatrix} \quad k := 0..2$$

'Consequently' the analysis is continued with the averages

$$V_{S0.ave_k} := \frac{V_{S0.rat.s_{2k}} + V_{S0.rat.s_{2k+1}}}{2}$$

$$V_{S0.rat.s_{2k}} := V_{S0.ave_k}$$

$$V_{S0.rat.s_{2k+1}} := V_{S0.ave_k}$$

Check of current data

$$v_{S0.Errors_{i,j}} := \frac{V_{S0.rat_{i,j}} - V_{S0.rat.s_i}}{V_{S0.rat.s_i}}$$

$$\frac{v_{S0.Errors}}{\%} = \begin{bmatrix} -0.10 & 0.31 & -0.67 & 0.35 & -0.36 & 0.22 & 0.14 & 0.11 & 0.13 & 0.44 & 1.59 & -1.04 \\ 0.05 & -0.35 & 0.53 & -0.28 & 0.21 & -0.23 & 0.15 & -0.05 & -0.60 & -0.16 & -2.01 & 1.19 \\ 0.00 & 0.25 & -0.22 & 0.12 & -0.02 & 0.15 & -0.32 & -0.01 & 0.76 & -0.13 & 1.59 & -0.86 \\ -0.12 & -0.21 & -0.12 & -0.05 & -0.21 & -0.14 & 0.36 & -0.00 & -0.86 & 0.28 & -1.14 & 0.44 \\ -0.06 & -0.06 & 0.05 & -0.21 & 0.07 & -0.10 & -0.54 & -0.21 & 0.58 & -0.53 & 0.55 & -0.39 \\ -0.02 & 0.11 & -0.31 & 0.25 & -0.22 & 0.12 & 0.45 & 0.17 & -0.47 & 0.55 & 0.06 & -0.08 \end{bmatrix}$$

Check of power data

$$P_{C_{i,j}} := P_{sup}(p_{rat.s}, N_{i,j}, V_{S0.rat.s_i})$$

$$P_{S.Errors_{i,j}} := \frac{P_{S_{i,j}} - P_{C_{i,j}}}{P_{C_{i,j}}}$$

$$\frac{\text{P S.Errors}}{\%} = \begin{bmatrix} -0.54 & -0.01 & 0.18 & 0.02 & 0.03 & -0.66 & -0.23 & -0.63 & -0.10 & 0.18 & -4.28 & 0.04 \\ 0.14 & -0.14 & -0.26 & 0.50 & -0.05 & -0.16 & -0.39 & -0.25 & 0.19 & 0.13 & -0.11 & -0.03 \\ 0.15 & -0.04 & 0.31 & 0.10 & 0.22 & -0.32 & 0.21 & 0.33 & -0.65 & 0.30 & -1.73 & 1.36 \\ -0.20 & 0.31 & -0.07 & 0.26 & 0.10 & -0.19 & -0.42 & -0.08 & 0.35 & 0.91 & 0.09 & -0.03 \\ -0.25 & 0.88 & -0.15 & 0.28 & -0.04 & -0.10 & 0.39 & 0.19 & -0.30 & 0.48 & -0.20 & -0.24 \\ 0.08 & 0.30 & 0.31 & -0.02 & 0.31 & -0.22 & -0.44 & -0.03 & 0.29 & -0.34 & -0.12 & 0.07 \end{bmatrix}$$

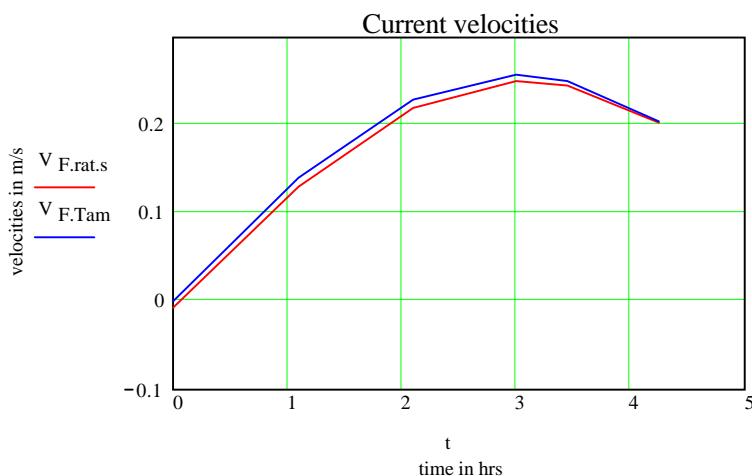
These errors indicate that the test data are not just noisy!

**And in this case the data used for the construction of the test data are known,
so that further comparison of the overall results with 'input' is possible.**

Current

$$T := 12 \cdot \text{hr} \quad T := \frac{T}{\text{hr}} \quad A := 0.5 \cdot \text{kn} \quad A := \frac{A}{\text{m} \cdot \text{sec}^{-1}} \quad V_F(\tau) := A \cdot \sin\left(\frac{2 \cdot \pi}{T} \cdot \tau\right)$$

$$i := 0 .. \text{last}(t) \quad V_{F.Tam_i} := V_F(t_i)$$



$$\frac{V_{F.rat.s} - V_{F.Tam}}{A \cdot \%} = \begin{bmatrix} -2.743 \\ -3.763 \\ -3.637 \\ -2.685 \\ -1.970 \\ -0.460 \end{bmatrix}$$

Power ratios

Data at no wind and no waves

$$V_{S0.Tam} := \begin{bmatrix} 14 \\ 16 \\ 17 \end{bmatrix} \cdot \text{kn} \quad N_{S0.Tam} := \begin{bmatrix} 88.9 \\ 103.7 \\ 112.1 \end{bmatrix} \cdot \frac{1}{\text{min}} \quad P_{S0.Tam} := \begin{bmatrix} 8207 \\ 13226 \\ 16938 \end{bmatrix} \cdot \text{mhp}$$

$$V_{S0.Tam} := \frac{V_{S0.Tam}}{\text{m} \cdot \text{sec}^{-1}} \quad N_{S0.Tam} := \frac{N_{S0.Tam}}{\text{Hz}} \quad P_{S0.Tam} := \frac{P_{S0.Tam}}{\text{W}}$$

$$i := 0 .. 2$$

Powering characteristic identified

$$A_{Tam_{i,0}} := \left(N_{SO.Tam_i} \right)^3$$

$$A_{Tam_{i,1}} := \left(N_{SO.Tam_i} \right)^2 \cdot V_{SO.Tam_i}$$

$$P_{Tam} := \text{LeftInv}(A_{Tam}) \cdot P_{SO.Tam}$$

$$P_{Tam}(N, V) := p_{Tam_0} \cdot N^3 + p_{Tam_1} \cdot N^2 \cdot V$$

$$J_H := \begin{bmatrix} 0.691 \\ 0.749 \end{bmatrix}$$

$$k_{P.Tam_0} := \frac{p_{Tam_0}}{\rho \cdot D^5}$$

$$k_{P.Tam_1} := \frac{p_{Tam_1}}{\rho \cdot D^4}$$

$$p_{Tam} = \begin{bmatrix} 3.34 \cdot 10^6 \\ -306195.70 \end{bmatrix}$$

$$k := 0..1$$

$$k_{P.rat.s_0} := \frac{p_{rat.s_0}}{\rho \cdot D^5}$$

$$k_{P.rat.s_1} := \frac{p_{rat.s_1}}{\rho \cdot D^4}$$

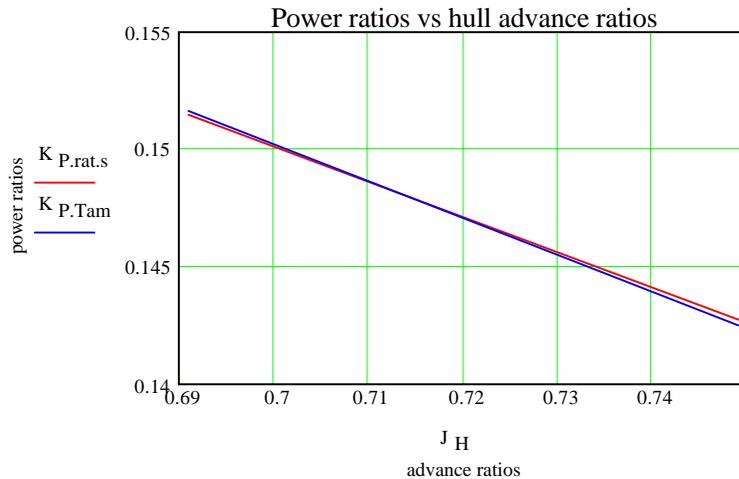
$$p_{rat.s} = \begin{bmatrix} 3.28 \cdot 10^6 \\ -292283.14 \end{bmatrix}$$

$$K_{P.Tam_k} := k_{P.Tam_0} + k_{P.Tam_1} \cdot J_{H_k}$$

$$k_{P.Tam} = \begin{bmatrix} 0.26 \\ -0.16 \end{bmatrix}$$

$$K_{P.rat.s_k} := k_{P.rat.s_0} + k_{P.rat.s_1} \cdot J_{H_k}$$

$$k_{P.rat.s} = \begin{bmatrix} 0.26 \\ -0.15 \end{bmatrix}$$



Despite the inconsistencies observed, the overall results are nearly identical with the input data of the simulation.

Power required

Absolute wind speeds

$$V_{WindA.10} := 10 \cdot kn$$

$$V_{WindA.10} := \frac{V_{WindA.10}}{m \cdot sec^{-1}}$$

$$V_{WindA.20} := 20 \cdot kn$$

$$V_{WindA.20} := \frac{V_{WindA.20}}{m \cdot sec^{-1}}$$

Absolute wind directions

$$\Psi_{WindA} := \begin{bmatrix} 0 \\ 30 \\ 45 \\ 60 \\ 75 \\ 90 \end{bmatrix} \cdot deg$$

$$\Psi_{WindA} := \frac{\Psi_{WindA}}{rad}$$

Relative wind velocity

in longitudinal direction

$$i := 0 .. ni - 1 \quad j := 0 .. ni - 1$$

$$V_{WindA.x.10_j} := V_{WindA.10} \cdot \cos(\Psi_{WindA_j})$$

$$V_{WindA.x.20_j} := V_{WindA.20} \cdot \cos(\Psi_{WindA_j})$$

$$V_{WindR.x_{i,j}} := V_{G_i} + V_{WindA.x.10_j} \cdot \text{if}(\Psi_{0_i} < \pi, 1, -1)$$

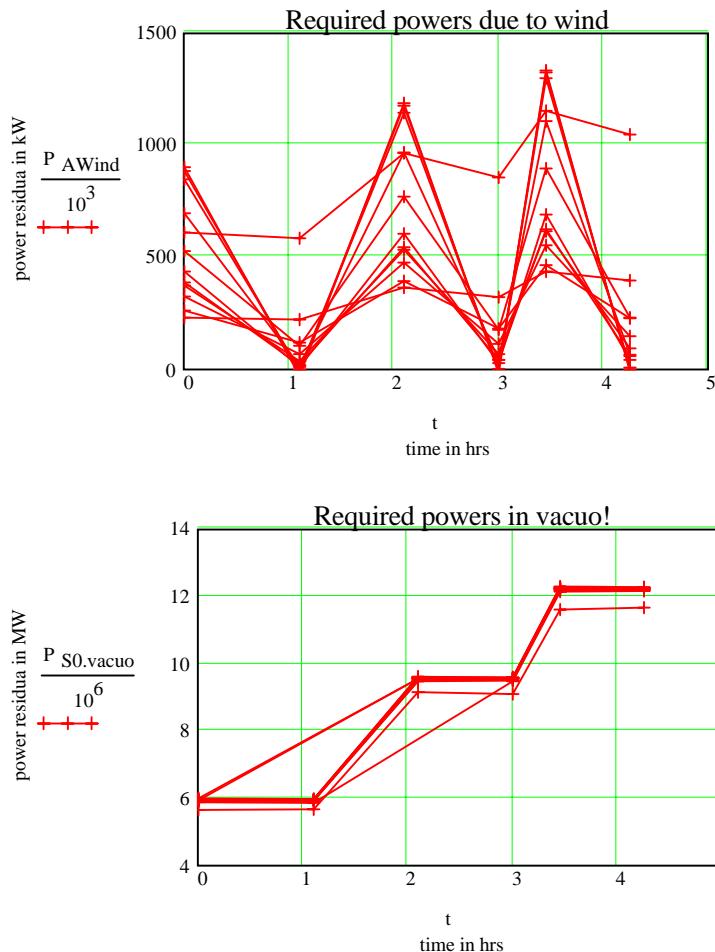
$$V_{WindR.x_{i,ni+j}} := V_{G_i} + V_{WindA.x.20_j} \cdot \text{if}(\Psi_{0_i} < \pi, 1, -1)$$

Evaluation

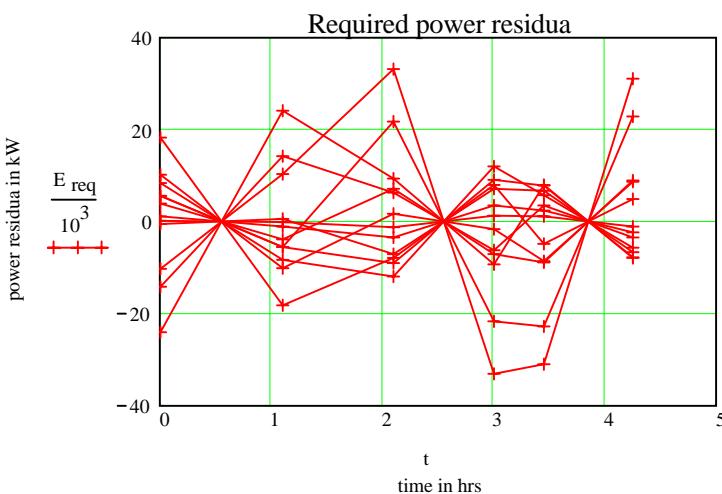
$$j := 0 .. nj - 1$$

$$Res_{req_j} := \text{Required}(V_{S0.rat.s}, P_S^{<j>}, V_{WindR.x}^{<j>})$$

$$[E_{req}^{<j>} \quad P_{AWind}^{<j>} \quad P_{S0.vacuo}^{<j>} \quad C_{Res}^{<j>}] := Res_{req_j}$$



**With one exception, run 11 (2 - 6), all runs provide
very closely the same power required in vacuo!**

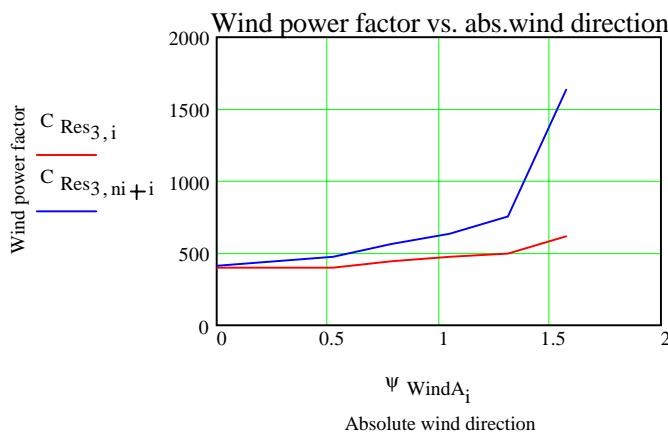


$$\frac{E_{\text{req}}}{10^3} = \begin{bmatrix} -1 & 1 & 0 & -14 & 8 & 6 & 10 & -24 & 4 & 18 & 6 & -10 \\ 1 & -1 & -0 & 14 & -8 & -6 & -10 & 24 & -4 & -18 & -6 & 10 \\ -7 & -3 & -1 & 6 & -12 & -9 & 2 & 9 & 7 & -8 & 22 & 33 \\ 7 & 3 & 1 & -6 & 12 & 9 & -2 & -9 & -7 & 8 & -22 & -33 \\ 7 & 2 & 1 & 3 & 6 & 8 & -9 & 8 & -9 & -5 & -23 & -31 \\ -7 & -2 & -1 & -3 & -6 & -8 & 9 & -8 & 9 & 5 & 23 & 31 \end{bmatrix}$$

The pattern exhibited by the residua is an indication, that in simulation of the data another law has been used than in my evaluation.

So statistical analysis is not meaningful at this stage, particularly in view of the very small residua!

The intermediate step of the power in vacuo, the power required due to water resistance, is necessary due to the fact, that the coefficients of wind resistance are different depending on the wind direction, in the present investigation **stupidly** taken to be the absolute direction.



This plot shows that something is wrong with the data of the last run, as has been observed before. **Consequently the results of the last run are being excluded from the following evaluation.**

Power required at no wind

In order to determine the power in still air the value at zero angle has to be taken.

$$C_{\text{Res.Air}} := \frac{C_{\text{Res}_{3,0}} + C_{\text{Res}_{3,6}}}{2} \quad C_{\text{Res.Air}} = 403.0$$

$$P_{AAir_i} := C_{\text{Res.Air}} \cdot (V_{S0.rat.s_i})^3$$

$$P_{S0.rat_{i,j}} := P_{S0.vacuo_{i,j}} + P_{AAir_i}$$

$$P_{S0.rat.s_i} := \text{mean} \left[(P_{S0.rat})^{<i>} \right]$$

Averages

$$i := 0 .. \frac{ni}{2} - 1$$

$$j := 0 .. nj - 2$$

$$P_{S0.ave_{i,j}} := \frac{P_{S0.rat_{2i,j}} + P_{S0.rat_{2i+1,j}}}{2}$$

$$\frac{P_{S0.ave}}{10^6} = \begin{bmatrix} 6.06 & 6.09 & 6.09 & 6.09 & 6.13 & 6.10 & 6.01 & 6.09 & 6.11 & 6.13 & 6.11 \\ 9.73 & 9.77 & 9.78 & 9.81 & 9.81 & 9.71 & 9.69 & 9.82 & 9.79 & 9.79 & 9.81 \\ 12.45 & 12.50 & 12.50 & 12.53 & 12.54 & 12.47 & 12.42 & 12.56 & 12.49 & 12.53 & 12.49 \end{bmatrix}$$

$$P_{S0.ave.mean_i} := \text{mean}\left[\left(P_{S0.ave}^T\right)^{*}*$$

$$P_{S0.ave.mean} = \begin{bmatrix} 6.09 \\ 9.77 \\ 12.50 \end{bmatrix} \circ \frac{MW}{W}$$

$$P_{S0.ave.dev_i} := \text{Stdev}\left[\left(P_{S0.ave}^T\right)^{*}*$$

$$P_{S0.ave.dev} = \begin{bmatrix} 0.03 \\ 0.04 \\ 0.04 \end{bmatrix} \circ \frac{MW}{W}$$

$$P_{S0.95_i} := \frac{2 \cdot P_{S0.ave.dev_i}}{P_{S0.ave.mean_i}}$$

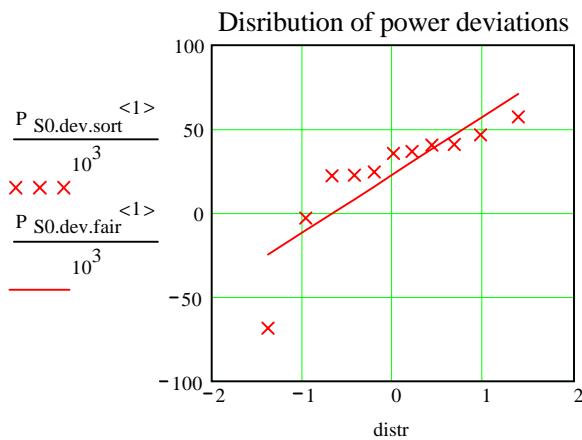
$$P_{S0.95} = \begin{bmatrix} 1.10 \\ 0.88 \\ 0.64 \end{bmatrix} \circ \%$$

95 % confidence interval less than 1 %
for all runs, except 11 (2 - 6)!

Analysis of distribution of deviations over all runs

$$P_{S0.rat.dev}^{} := P_{S0.rat}^{} - P_{S0.rat.s}$$

$$\begin{bmatrix} \text{distr}^{*} \\ P_{S0.dev.sort}^{*} \\ P_{S0.dev.fair}^{*} \\ \text{par}^{*} \end{bmatrix} := \text{Norm_distr}\left[\left(P_{S0.rat.dev}^T\right)^{*}*****$$



Just an example to show that the deviations over all runs are **not** normally distributed.

Comparison with the input

$$p_{\text{diff}} := \frac{P_{S0.\text{ave}.mean_i} - P_{S0.Tam_i}}{P_{S0.Tam_i}}$$

$$p_{\text{diff}} = \begin{bmatrix} 0.93 \\ 0.47 \\ 0.33 \end{bmatrix} \cdot \%$$

Less than 1 % difference from input values

Mean power polynomial coefficients

$$C_{\text{Res.mean}_i} := \text{mean}\left[\left(C_{\text{Res}}^T\right)^{*} \right]*$$

$$C_{\text{Res.mean}_2} := C_{\text{Res.mean}_2} + C_{\text{Res.Air}}$$

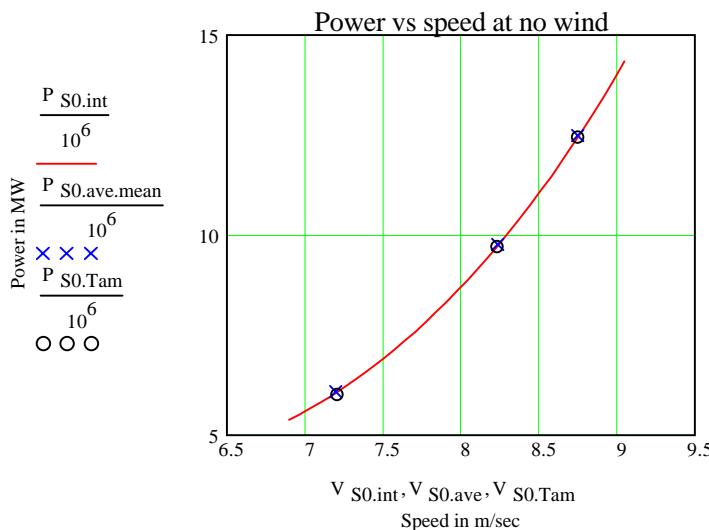
$$C_{\text{Res.mean}} = \begin{bmatrix} 3.85 \cdot 10^6 \\ -1.07 \cdot 10^6 \\ 90081.58 \end{bmatrix}$$

Interpolated power values

$$n := 32 \quad k := 0..n \quad \Delta V_{S0} := 0.3$$

$$V_{S0.int_k} := V_{S0.ave_0} - \Delta V_{S0} + k \cdot \frac{\left(V_{S0.ave_2} - V_{S0.ave_0}\right) + 2 \cdot \Delta V_{S0}}{n}$$

$$P_{S0.int_k} := P_{\text{req}}\left(C_{\text{Res.mean}}, V_{S0.int_k}\right)$$



Normalised values

$$F_{n int_k} := F_n\left(V_{S0.int_k}\right)$$

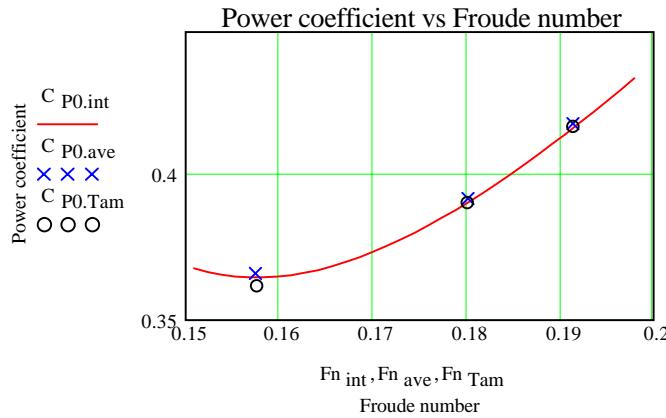
$$C_{P0.int_k} := CP\left(P_{S0.int_k}, V_{S0.int_k}\right)$$

$$F_{n ave_i} := F_n\left(V_{S0.ave_i}\right)$$

$$C_{P0.ave_i} := CP\left(P_{S0.ave.mean_i}, V_{S0.ave_i}\right)$$

$$F_{n Tam_i} := F_n\left(V_{S0.Tam_i}\right)$$

$$C_{P0.Tam_i} := CP\left(P_{S0.Tam_i}, V_{S0.Tam_i}\right)$$



Frequencies of revolution

$$N_{init} := 1$$

$$N_{S0.ave}^{<j>} := Revs(p_{rat}^{<j>}, V_{S0.ave}, P_{S0.ave}^{<j>}, N_{init})$$

$$60 \cdot N_{S0.ave} = \begin{bmatrix} 89.0 & 89.1 & 89.1 & 89.0 & 89.2 & 89.2 & 88.8 & 89.1 & 89.2 & 89.1 & 89.8 \\ 103.7 & 103.8 & 103.8 & 103.8 & 103.9 & 103.7 & 103.6 & 104.0 & 103.9 & 103.7 & 104.3 \\ 112.1 & 112.0 & 112.2 & 112.3 & 112.3 & 112.2 & 112.1 & 112.4 & 112.2 & 112.2 & 112.3 \end{bmatrix}$$

$$N_{S0.ave.s} := Revs(p_{rat.s}, V_{S0.ave}, P_{S0.ave.mean}, N_{init})$$

$$N_{S0.ave.s} = \begin{bmatrix} 89.09 \\ 103.82 \\ 112.22 \end{bmatrix} \circ \frac{\text{sec}}{\text{min}}$$

$$N_{S0.ave.mean_i} := \text{mean}\left[\left(N_{S0.ave}^T\right)^{<i>}\right]$$

$$N_{S0.ave.mean} = \begin{bmatrix} 89.2 \\ 103.8 \\ 112.2 \end{bmatrix} \circ \frac{\text{sec}}{\text{min}}$$

$$N_{S0.ave.dev_i} := \text{Stdev}\left[\left(N_{S0.ave}^T\right)^{<i>}\right]$$

$$N_{S0.ave.dev} = \begin{bmatrix} 0.243 \\ 0.177 \\ 0.095 \end{bmatrix} \circ \frac{\text{sec}}{\text{min}}$$

$$n_{ave.95_i} := \frac{2 \cdot N_{S0.ave.dev_i}}{N_{S0.ave.mean_i}}$$

$$n_{ave.95} = \begin{bmatrix} 0.55 \\ 0.34 \\ 0.17 \end{bmatrix} \circ \%$$

96 % confidence interval less than +/- 0.6 %
for all runs, except 11 (2 - 6)!

Analysis of distribution of deviations over all runs

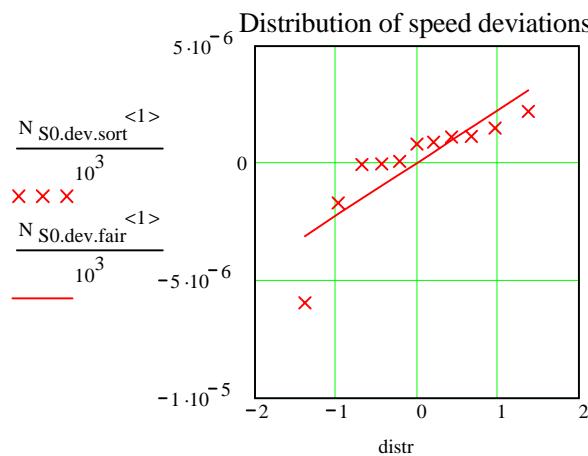
$i := 0 .. n_i - 1$

$N_{init_i} := 1$

$N_{S0.rat^{<j>}} := Revs(p_{rat.s}, V_{S0.rat.s}, P_{S0.rat^{<j>}}, N_{init})$

$N_{S0.rat.s_i} := \text{mean}\left[\left(N_{S0.rat}^T\right)^{<i>}\right]$

$N_{S0.dev^{<j>}} := N_{S0.rat^{<j>}} - N_{S0.rat.s}$

$$\begin{bmatrix} distr^{<i>} \\ N_{S0.dev.sort}^{<i>} \\ N_{S0.dev.fair}^{<i>} \\ par^{<i>} \end{bmatrix} := \text{Norm_distr}\left[\left(N_{S0.dev}^T\right)^{<i>}\right]$$


Just an example to show that the deviations over all runs are **not** normally distributed.

Comparison with the input

$i := 0 .. 2$

$$n_{diff_i} := \frac{N_{S0.ave.s_i} - N_{S0.Tam_i}}{N_{S0.Tam_i}}$$

$$n_{diff} = \begin{bmatrix} 0.21 \\ 0.11 \\ 0.10 \end{bmatrix} \cdot \%$$

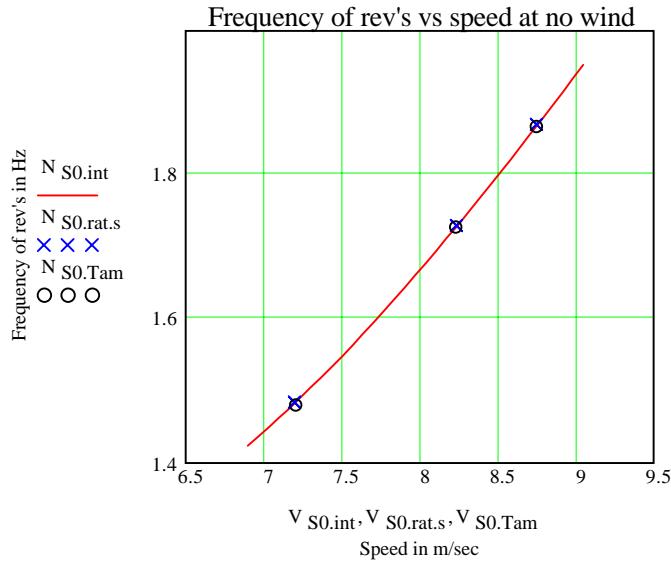
Less than +/- 0.3 % difference from input values

Interpolated values

$N_{init_k} := 1$

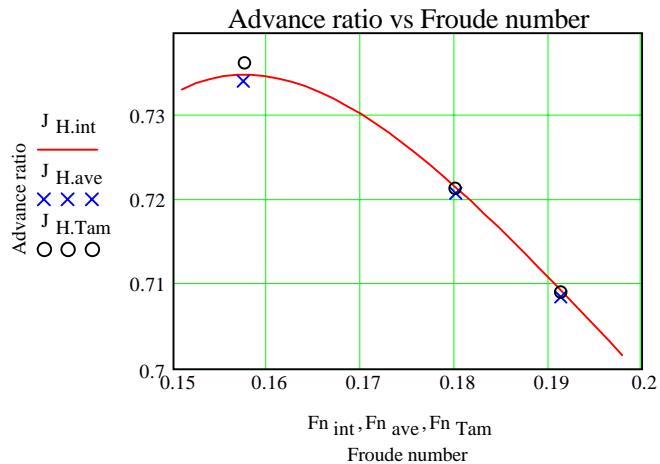
$N_{S0.int} := Revs(p_{rat.s}, V_{S0.int}, P_{S0.int}, N_{init})$

$$N_{S0.ave.s} = \begin{bmatrix} 1.48 \\ 1.73 \\ 1.87 \end{bmatrix}$$



Normalised values

$$\begin{aligned} J H_{int_k} &:= JH(V S0.int_k, N S0.int_k) \\ J H_{ave_i} &:= JH(V S0.ave_i, N S0.ave.s_i) \\ J H_{Tam_i} &:= JH(V S0.Tam_i, N S0.Tam_i) \end{aligned}$$



Some Comments

The individual and the overall results concerning the power required are perfect for any practical purpose, even with the stupid wind power model adopted. But I am reluctant to adopt

a more involved model and to identify more than four parameters from only six runs, particularly from real data.

A problem is that one needs the ahead wind coefficient, which has been identified in this test case from the appropriate tests at wind from ahead and from behind. In practice one will have to identify this value accordingly, if one does not want to rely on 'laws' etc.

The individual results concerning the power supplied and the current are much less satisfactory due to poor quality of the data. In general one does not have the excellent overall results from a large sample as in the present test case. In practice one needs good data and, as examples have shown, usually they are good nowadays.

My suspicion is that the procedure for the construction of the data includes inconsistencies as does the traditional procedure for the analysis, as e. g. the procedure proposed in the draft standard ISO DIS 15016. I have provided evidence to that effect already at an early stage of the discussion and continued to explain this in many examples, papers and presentations all to be found on my website.

The important point of the whole procedure is that the properties of the ship can be identified without reference to model test results and other prior knowledge. A problem is the tendency towards smaller number's of runs for reasons of costs. As I pointed out many times quasi-steady changes of state will provide all the information required. One does not even need three double runs. Maybe people will use the method as soon as they realise that its not only more convincing but also reducing their costs.

END Analysis of EVEREST constructed data